

# Causal Model-Based Contextuality

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# Overview

- Extending contextuality to inconsistently connected systems
- Multimaximal couplings of contextuality-by-default (CbD; Dzhafarov & Kujala, 2017)
  - Physical interpretation? Implications for theory?
- Probabilistic causal models (Cavalcanti, 2018)  
Generalizes original hidden-variables approach (Bell, 1964; Fine, 1982; Einstein, Podolsky, & Rosen, 1935; Kochen & Specker, 1967)
- Prove equivalence of 3 definitions of extended contextuality, including CbD's

# Setup (adapted from Kujala et al., 2015)

- **Measurement system**  $M = \{M_q^c: q < c\}$ 
  - Observables (contents)  $\mathcal{Q} = \{q\}$
  - Contexts  $\mathcal{C} = \{c\}$
  - Outcome space  $\mathcal{O}_q$  for each  $q$  (assumed finite)
  - Measurements  $M_q^c$  for  $q < c$
  - Distributions  $\mu_c$  on  $\prod_{q < c} \mathcal{O}_q$  for  $M^c = \{M_q^c: q < c\}$
- **Standard contextuality**
  - Consistently connected:  $M_q^c \sim M_q^{c'}$  for all  $c, c' > q$
  - No global distribution on  $\prod_{q \in \mathcal{Q}} \mathcal{O}_q$  compatible with all  $\mu_c$

# Contextuality with Inconsistent Connectedness

- Motivation (Kujala et al., 2015; Dzhafarov & Kujala, 2015, 2016)
  - Difficult to avoid in experimental practice
  - Generally present in finite samples
  - Essential to certain systems of interest
- CbD approach (Kujala et al., 2015; Dzhafarov & Kujala, 2016, 2017)
  - Influence of context beyond direct influence
  - $M_q^C, M_q^{C'}$  differ more than mandated by their distributions
  - **No-conspiracy principle** (Cervantes & Dzhafarov, 2018): Direct influences do not cancel out in empirical distributions

# Present Contribution

- Define direct influence within probabilistic causal models
  - Theory-dependent, distinct from inconsistent connectedness
- Formalize no-conspiracy principle
  - No **crossed influences**: Opposite direct influences for different latent states of system
- Prove equivalence of three forms of contextuality (formalizing 1 & 2)
  1. Modeling full system requires more direct influence than modeling each observable
  2. Modeling system requires violating no-conspiracy principle
  3. CbD definition based on multimaximal couplings
  - All reduce to standard contextuality for consistently connected systems

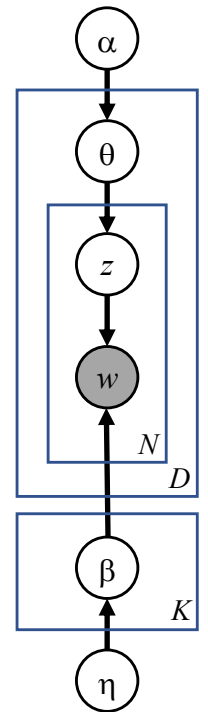
# Probabilistic Causal Models

- Powerful tool from statistics, machine learning, psychology (Jordan, 1999; Pearl, 2000; Tenenbaum et al., 2011)

$$\mathcal{X} = \{X_i\} \quad \forall i, Pa(X_i) \subset \mathcal{X}$$

$$\Pr[\mathcal{X}] = \prod_i \Pr[X_i | Pa(X_i)]$$

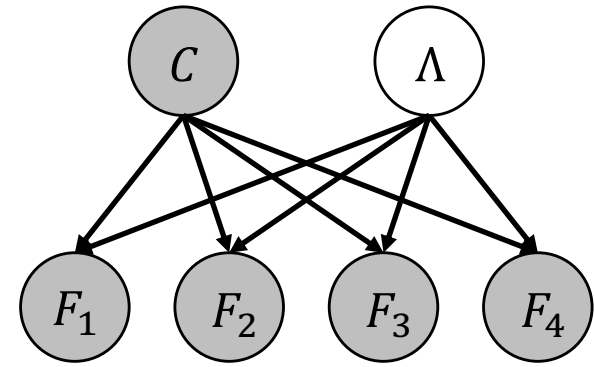
- Acyclic directed graph,  $X_j \in Pa(X_i)$
- Joint distribution factors into causal dependencies
- Includes observed and latent (hidden) variables
- Natural extension of hidden-variables models
  - Valuable framework for studying contextuality (Cavalcanti, 2018)



LDA:  
Blei, Ng,  
& Jordan  
(2003)

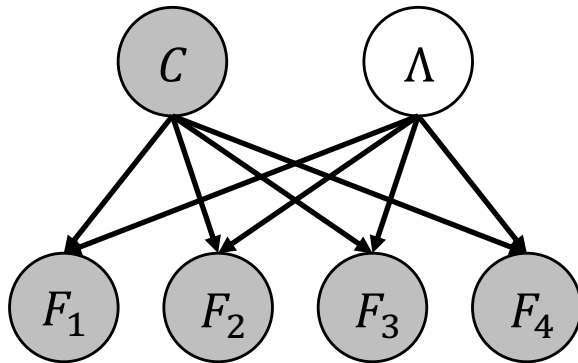
# Canonical Causal Models

- Context, latent state, and observables
  - $\mathcal{M} = (C, \Lambda, \{F_q\})$
  - $Pa(\Lambda) = Pa(C) = \emptyset$
  - $Pa(F_q) = \{C, \Lambda\}$
  - $C$  treated as index variable
- Deterministic observables (Fine, 1982)
  - $F_q(c, \lambda) \in \mathcal{O}_q$
  - No loss of expressive power: push stochasticity into  $\Lambda$
- Model  $\mathcal{M}$  for a system  $M$  (cf. couplings in CbD; Kujala et al., 2015)
  - $\Pr[\{F_q: q < c\} | C = c] = \mu_c$  for all  $c$

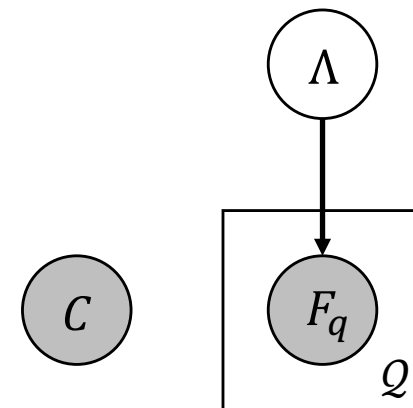
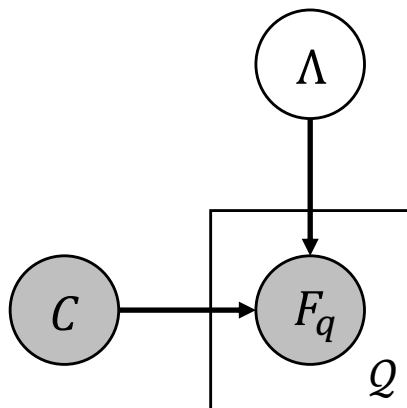
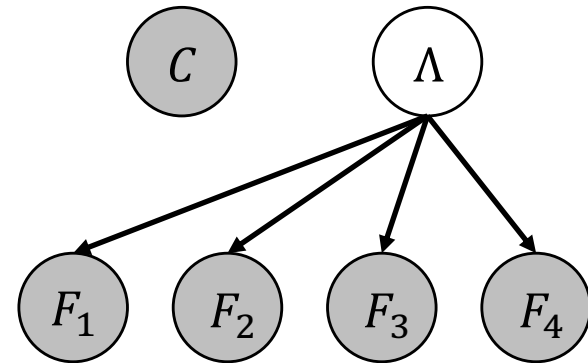


# Canonical Causal Models

General



Context-free





# Canonical Causal Models and Standard Contextuality

- **Proposition 1.** For any measurement system  $M$ , there exists a canonical causal model  $\mathcal{M}$  that is a model for  $M$ .
- **Proposition 2 (Fine, 1982).** A consistently connected measurement system is noncontextual iff there exists a context-free model of that system.
- **Proposition 3.** A measurement system  $M$  is consistently connected iff there exist context-free models for the single-observable subsystems  $M_q = \{M_q^c : q < c\}$  for all  $q$ .

# Direct Influence in Causal Models

- **Direct influence:** Given  $\mathcal{M}$ ,  $q$ , and  $\{c, c'\} \succ q$ :

$$\Delta_{c,c'}(F_q) = \Pr[\{\lambda: F_q(\lambda, c) \neq F_q(\lambda, c')\}]$$

- Probability of latent state for which context change affects measurement outcome

- **Crossed influences**

$$\Pr[\{\lambda: F_q(\lambda, c) = v, F_q(\lambda, c') \neq v\}] > 0$$

$$\Pr[\{\lambda: F_q(\lambda, c) \neq v, F_q(\lambda, c') = v\}] > 0$$

- **Aligned model**

- No crossed influences, for any  $q$ ,  $v \in \mathcal{O}_q$ ,  $\{c, c'\} \succ q$
- Formalizes Cervantes & Dzhafarov's (2018) no-conspiracy principle

# Example: Popescu-Rohrlich Box

$M$

$\Pr[M_q^c = 1]$	$A_1$	$B_1$	$A_2$	$B_2$
$c_{11}$	$1/2$	$1/2$		
$c_{21}$		$1/2$	$1/2$	
$c_{22}$			$1/2$	$1/2$
$c_{12}$	$1/2$			$1/2$

$\Pr[M_q^c = M_{q'}^c]$		$q'$
	$B_1$	$B_2$
$q$	$A_1$	$1 \quad 0$
	$A_2$	$1 \quad 1$

$\mathcal{M}$

	$\lambda_1$	$\lambda_2$	
$\Pr[\Lambda = \lambda]$	$1/2$	$1/2$	
$F_{A_1}(c_{11}, \lambda)$	$1$	$-1$	} $\Delta_{c_{11}, c_{12}}(F_{A_1}) = 0$
$F_{A_1}(c_{12}, \lambda)$	$1$	$-1$	
$F_{B_1}(c_{11}, \lambda)$	$1$	$-1$	} $\Delta_{c_{11}, c_{21}}(F_{B_1}) = 1$
$F_{B_1}(c_{21}, \lambda)$	$-1$	$1$	
$F_{A_2}(c_{21}, \lambda)$	$-1$	$1$	} $\Delta_{c_{21}, c_{22}}(F_{A_2}) = 0$
$F_{A_2}(c_{22}, \lambda)$	$-1$	$1$	
$F_{B_2}(c_{12}, \lambda)$	$-1$	$1$	} $\Delta_{c_{12}, c_{22}}(F_{B_2}) = 0$
$F_{B_2}(c_{22}, \lambda)$	$-1$	$1$	

# Model-based Contextuality

- **M-contextuality**

- Given any model  $\mathcal{M}$  for  $M$ , there exist  $c, c' \succ q$  such that  $\Delta_{c,c'}(F_q)$  is greater than necessary

- **M-noncontextuality**

- $\mathcal{M}$  simultaneously minimizes  $\Delta_{c,c'}(F_q)$  for all  $c, c' \succ q$

- Formalizes 2<sup>nd</sup> notion of extended contextuality

- Modeling full system requires more direct influence than modeling each observable

# Model-based Contextuality

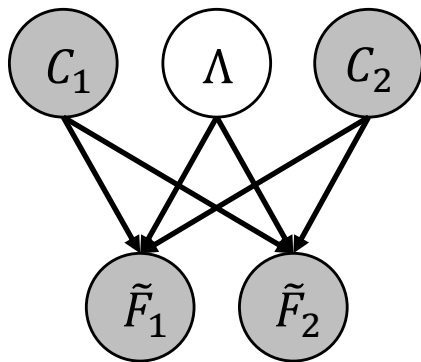
- **Theorem 1.** If  $M$  is consistently connected, then  $M$  is  $M$ -contextual iff it is contextual
  - Follows from Propositions 2 and 3
- **Proposition 4.** Given  $M$  and  $q < c, c'$ , the minimum direct influence over all models  $\mathcal{M}$  for  $M$  is:

$$\min_{\mathcal{M}} \Delta_{c,c'}(F_q) = 1 - \sum_{v \in \mathcal{O}_q} \min\{\Pr[M_q^c = v], \Pr[M_q^{c'} = v]\}$$

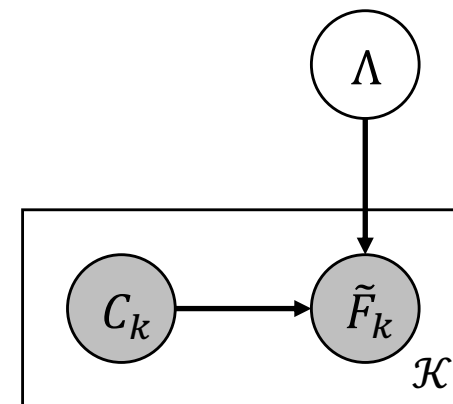
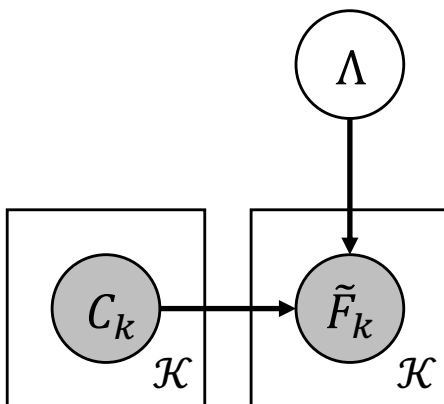
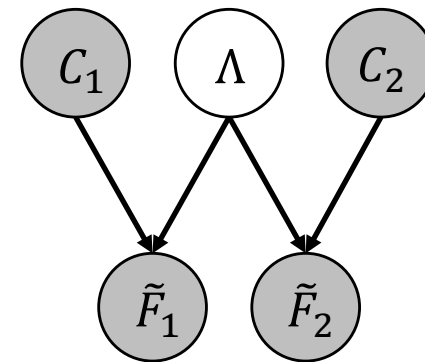
- **Theorem 2.** For any  $M$ ,  $M$  is  $M$ -noncontextual iff it admits an aligned model
  - $M$ -contextual iff all models contain crossed influences
  - Crossed influence implies  $\Delta_{c,c'}(F_q)$  can be reduced

# Partitionable Systems

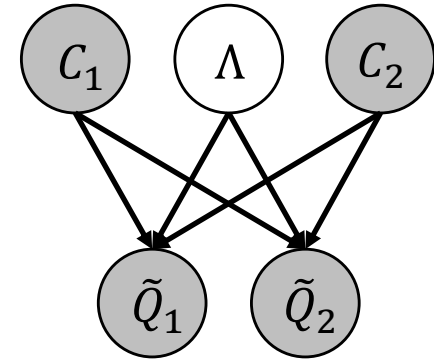
Signaling



No Signaling



# Partitionable Systems



- **Partitionable system**

- Observers:  $\mathcal{K} = \{k\}$
- Partition of observables:  $\mathcal{Q} = \sqcup_k \mathcal{Q}_k$
- Factoring of contexts:  $c = (c_k: k \in \mathcal{K}), c_k \in \mathcal{Q}_k$

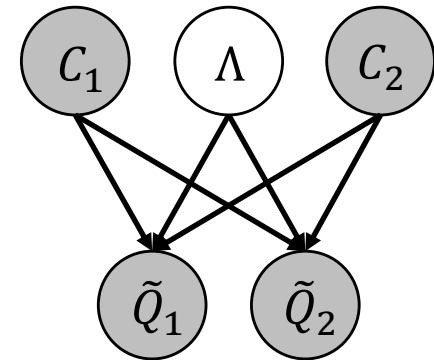
- **Partitioned model**

- $\tilde{\mathcal{M}} = (\{C_k\}, \Lambda, \{\tilde{F}_k\})$
- $\tilde{F}_k(\lambda, c) = F_{c_k}(\lambda, c)$

- **Signaling**

- $\tilde{\Delta}_{c,c'}(\tilde{F}_k) = \Pr[\{\lambda: \tilde{F}_k(\lambda, c) \neq \tilde{F}_k(\lambda, c')\}] = \Delta_{c,c'}(F_{c_k})$   
for  $c_k = c'_k$

# Partitionable Systems



- Parallel results:
- Any partitionable system admits a partitioned model
- A consistently connected system is noncontextual iff it admits a model with no signaling,  $\tilde{F}_k(\lambda, c) = \tilde{F}_k(\lambda, c_k)$
- $M$  is  $M$ -noncontextual iff a model  $\tilde{\mathcal{M}}$  minimizes  $\tilde{\Delta}_{c,c'}(\tilde{F}_k)$  for all  $k, c, c'$  ( $c_k = c'_k$ )
- $M$  is  $M$ -noncontextual iff it admits a model  $\tilde{\mathcal{M}}$  without crossed signals



# M-contextuality and CbD-contextuality

- Probabilistic coupling (Kujala et al., 2015; Thorisson, 2000)
  - Jointly distributed  $\{S_q^c: q < c\}$  with  $S^c \sim M^c$  for all  $c$
- Multimaximal coupling (Dzhafarov & Kujala, 2017)
  - Simultaneously maximizes  $\Pr[S_q^c = S_q^{c'}]$  for all  $q < c, c'$
- CbD-contextuality: Non-existence of multimaximal coupling
- **Theorem 3.** M-contextuality is equivalent to CbD-contextuality
  - Translation between models and couplings satisfying
$$\Delta_{c,c'}(F_q) = \Pr[S_q^c \neq S_q^{c'}]$$
- **Theorem 4.** A system is CbD-noncontextual iff it admits an aligned model

# A Challenge with Many-Valued Observables

- Cannot always simultaneously minimize all direct influences for a single observable, if not binary (Dzhafarov & Kujala, 2017):

	$v = 1$	$v = 2$	$v = 3$
$M_1^1$	0	$\frac{1}{2}$	$\frac{1}{2}$
$M_1^2$	$\frac{1}{2}$	0	$\frac{1}{2}$
$M_1^3$	$\frac{1}{2}$	$\frac{1}{2}$	0

- M-contextual and CbD contextual
- Remains so if dichotomized
- Violates intuition that contextuality has to do with what measurements are or are not made

# A Challenge with Many-Valued Observables

- Single measure of direct influence for each observable?
  - $\Delta(F_q|C) = \frac{1}{2} \sum_{c,c' \succ q} \Delta_{c,c'}(F_q)$
  - Violates intuition of monotonicity
- Definition of contextuality satisfying all of these axioms?
  - **Monotonicity** (Dzhafarov & Kujala, 2017): Subsystems of any noncontextual system are noncontextual
  - **Coarse-graining** (Dzhafarov & Kujala, 2017): Relabeling values of an observable in a non-contextual system,  $\mathcal{O} \rightarrow \mathcal{O}'$ , yields a noncontextual system
  - **Completeness**: A system with only one observable, or with all observables measured in every context, is noncontextual

# Conclusions

- Extends hidden-variable approaches (Cavalcanti, 2018)
- Physical/theoretical interpretation of CbD-contextuality
  - Formalizes Cervantes & Dzhafarov's no-conspiracy principle
- Value in translation, beyond specific definitions
  - Might facilitate solution to problem of complete systems
- Naturally suited for real (finite) datasets
  - $\{M_q^{c,i} : q < c, i \leq n_c\}$  – numbers, not random variables
  - Standard model evaluation and inferential statistics
- Distinction between inconsistent connectedness and direct influence
  - Empirical vs. theoretical
  - Atmanspacher & Filk (2019): non-communicating signaling
  - Inescapable: contextuality only meaningful with some exclusions on direct influence (e.g. spacelike separation)