

# Neither contextuality nor non-locality admits catalysts

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# Punchline

Let

- ▶  $d, e, f$  range over various correlations (contextual or not)
- ▶  $d \otimes e$  denote having  $d$  and  $e$  independently side-by-side
- ▶  $d \rightsquigarrow e$  denote the existence of a transformation  $d \rightarrow e$  in the resource theory of contextuality

## Theorem

*If  $d \otimes e \rightsquigarrow d \otimes f$ , then  $e \rightsquigarrow f$ . Ditto for the resource theory of non-locality.*

Contrast with entanglement, where catalysis is possible:

*'Entanglement-assisted local manipulation of pure quantum states'*

Jonathan, Plenio, PRL 1999.

# Overview

- ▶ As the resource theory of contextuality we use that of  
*'A comonadic view of simulation and quantum resources'*  
Abramsky, Barbosa, MK., Mansfield, LiCS 2019.  
giving a formalization of the the wirings and prior-to-input-classical communication paradigm studied in physics.
- ▶ The resource theory of non-locality: the n-partite version of the above
- ▶ Proof idea: if you can catalyze once you can catalyze arbitrarily many times. For big enough  $n$  this implies that one needs only a compatible (and hence non-contextual) part of  $d$ .<sup>1</sup>

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<sup>1</sup>or rather, a compatible subset of  $MP(d)$

## Formalising empirical data

A **measurement scenario**  $S = \langle X_S, \Sigma_S, O_S \rangle$ :

- ▶  $X_S$  – a finite set of measurements
- ▶  $\Sigma_S$  – a simplicial complex on  $X_S$   
faces are called the **measurement contexts**
- ▶  $O_S = (O_x)_{x \in X_S}$  – for each  $x \in X$  a non-empty outcome set  $O_x$ . Joint outcomes over  $U \subseteq X_S$  denoted by  $\mathcal{E}_S(U)$ .

An **empirical model**  $e = \{e_\sigma\}_{\sigma \in \Sigma}$  on  $S$ :

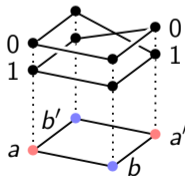
- ▶ each  $e_\sigma \in \text{Prob}(\mathcal{E}_S(U))$  is a probability distribution over joint outcomes for  $\sigma$ .
- ▶ *generalised no-signalling* holds: for any  $\sigma, \tau \in \Sigma_S$ , if  $\tau \subseteq \sigma$ ,

$$e_\sigma|_\tau = e_\tau$$

A	B	(0, 0)	(0, 1)	(1, 0)	(1, 1)
$a_0$	$b_0$	1/2	0	0	1/2
$a_0$	$b_1$	1/2	0	0	1/2
$a_1$	$b_0$	1/2	0	0	1/2
$a_1$	$b_1$	0	1/2	1/2	0

$$X = \{a_0, a_1, b_0, b_1\}, \quad O_x = \{0, 1\}$$

$$\Sigma = \downarrow \{ \{a_0, b_0\}, \{a_0, b_1\}, \{a_1, b_0\}, \{a_1, b_1\} \}.$$



## Contextuality

An empirical model  $e = \{e_\sigma\}_{\sigma \in \Sigma}$  on a measurement scenario  $(X, \Sigma, O)$  is **non-contextual** if there is a distribution  $d$  on  $\prod_{x \in X} O_x$  such that, for all  $\sigma \in \Sigma$ :

$$d|_\sigma = e_\sigma.$$

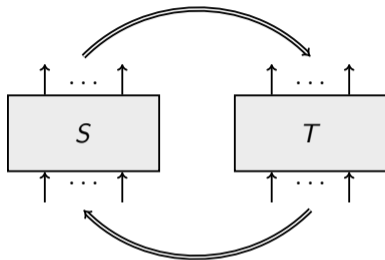
That is, we can **glue** all the local information together into a global consistent description from which the local information can be recovered.

If no such global distribution exists, the empirical model is **contextual**.

Contextuality: family of data that is **locally consistent** but **globally inconsistent**.

The import of Bell's and Kochen–Specker's theorems is that there are behaviours arising from quantum mechanics that are contextual.

## Maps between scenarios



A deterministic map  $S \rightarrow T$  proceeds as follows:

- ▶ map inputs of  $T$  (measurements) to inputs of  $S$
- ▶ run  $S$
- ▶ map outputs of  $S$  (measurement outcomes) to outputs of  $T$

## Same but formally

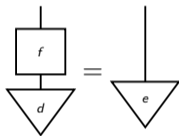
A deterministic map  $(\pi, h) : S \rightarrow T$  is given by:

- ▶ A simplicial function  $\pi : (X_T, \Sigma_T) \rightarrow (X_S, \Sigma_S)$ .
- ▶ For each  $x \in X_S$ , a function  $h_x : O_{\pi(y)} \rightarrow O_x$ .

Simpliciality of  $\pi$  means that contexts in  $\Sigma_T$  are mapped to contexts in  $\Sigma_S$ .

# Simulations

Given  $d : T$ ,  $e : S$ , a deterministic simulation  $d \rightarrow e$  is a deterministic map  $f : S \rightarrow T$  that transforms  $d$  to  $e$ .



For instance, the *PR*-box can be simulated from a liar's paradox on a triangle, by collapsing one edge to a point.

But what if we want to

- (i) let a measurement of  $T$  to depend on a measurement protocol of  $S$ ?
- (ii) use classical randomness?

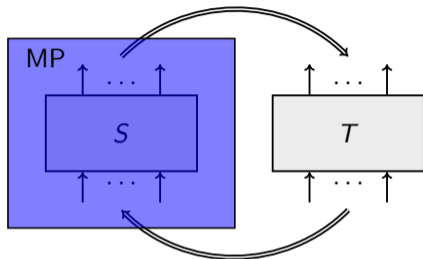


# The MP construction

Given a scenario  $S = \langle X_S, \Sigma_S, O_S \rangle$  we build a new scenario  $MP(S)$ , where:

- ▶ measurements are the (deterministic) measurement protocols on  $S$ . A measurement protocol on  $S$  is either empty or consists of a measurement in  $x \in X_S$  and of a function from outcomes of  $x$  to measurement protocols on  $S|_{I_k_x}$
- ▶ outcomes are the joint outcomes observed during a run of the protocol
- ▶ measurement protocols are compatible if they can be combined consistently

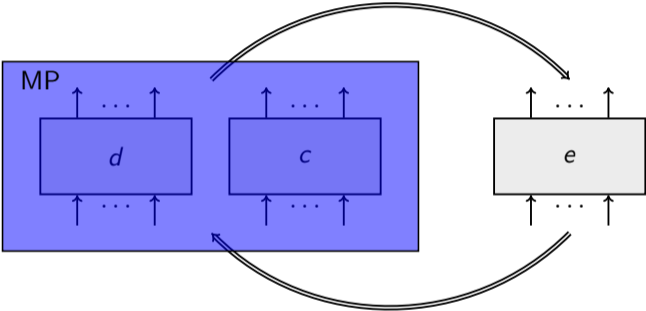
## Adaptive procedure



An adaptive map  $S \rightarrow T$  proceeds as follows:

- ▶ map measurements of  $T$  to **measurement protocols** over  $S$
- ▶ run  $S$
- ▶ map outcomes of  $MP(S)$  to outputs of  $T$

# Adaptive procedure with classical randomness



Requirement:  $c$  is noncontextual.

## General simulations

Given empirical models  $e$  and  $d$ , a **simulation** of  $e$  by  $d$  is a deterministic simulation

$$\text{MP}(d \otimes c) \rightarrow e$$

for some noncontextual model  $c$ .

The use of the noncontextual model  $c$  is to allow for classical randomness in the simulation.

We denote the existence of a simulation of  $e$  by  $d$  as  $d \rightsquigarrow e$ , read “ $d$  simulates  $e$ ”.

## Why bother?

The convertibility relation  $\rightsquigarrow$  results in a resource theory of contextuality with nice properties:

- ▶ Expressive enough to capture less formally defined transformations in the literature (in the single-shot exact case)
- ▶ Mathematically precise (at least in principle)
- ▶ Contextual fraction is a monotone
- ▶ Contextuality is equivalent to insimulability from a trivial model. Variants for logical and strong contextuality.

# No-catalysis

## Theorem (No-catalysis)

*If  $d \otimes e \rightsquigarrow d \otimes f$  then  $e \rightsquigarrow f$*

### Proof.

**First step — reduce to the deterministic case:**

If  $d \otimes e \rightsquigarrow d \otimes f$ , then there is a deterministic simulation  $\text{MP}(d \otimes e \otimes c) \rightarrow d \otimes f$  for some non-contextual  $c$ . Setting  $g := e \otimes c$  we thus have a deterministic map  $\text{MP}(d \otimes g) \rightarrow d \otimes f$ .

**Second step—if you can catalyze once, you can do so many times:** we can get deterministic simulations  $\text{MP}(d \otimes (g^{\otimes n})) \rightarrow d \otimes (f^{\otimes n})$  for any  $n$  so that the  $i$ -th copy of  $f$  uses  $d$  and the  $i$ -th copy of  $g$ , but otherwise the copies of  $f$  are simulated similarly.

## Concluding the proof

Cont.

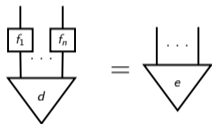
**Final step—things needed from  $d$  are compatible:** as the underlying map is simplicial, questions asked from  $d$  when simulating different copies of  $e$  are always compatible. Considering big enough  $n$ , this means that the set of all possible behaviours in  $d$  needed for the simulation forms a compatible subset of  $\text{MP}(d)$ . Join all of these to a single measurement protocol over  $d$  and simulate 1st copy of  $f$  by first measuring this single measurement of  $\text{MP}(d)$  and then proceeding to the 1st copy of  $g$ . This results in a deterministic simulation  $\text{MP}(d' \otimes g) \rightarrow f$ , where  $d'$  has a single measurement (representing the whole MP over  $d$ ) and is thus noncontextual.



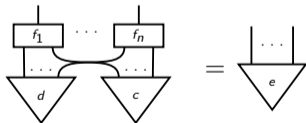
# Non-locality

We think of the resource theory of non-locality as an  $n$ -partite version of that of contextuality: an object is a model  $e : \bigotimes_{i=1}^n S_i$  over an  $n$ -partite scenario, and a simulation  $d \rightarrow e$  is an  $n$ -tuple of adaptive maps that, taken together, transform  $d$  to  $e$ .

In the deterministic case:



in the randomness-assisted case



where  $c$  is local. This captures the LOSR-paradigm.



## No catalysts for non-locality and beyond

For a minor variant of the previous proof, an  $n$ -partite simulation  $d \otimes e \rightarrow d \otimes f$  produces an  $n$ -partite simulation  $e \rightarrow f$ , proving the theorem for non-locality.

In fact, the proof shows more: if  $\mathcal{X}$  is a class of models that (i) contains all non-contextual models and (ii) is closed under  $\otimes$ , one can define  $\mathcal{X}$ -assisted simulations  $d \rightarrow e$  as deterministic simulations  $\text{MP}(d \otimes x) \rightarrow e$  where  $x \in \mathcal{X}$ . Write  $d \rightsquigarrow_{\mathcal{X}} e$  for the existence of such a simulation.

### Theorem

*For any such  $\mathcal{X}$ ,  $d \otimes e \rightsquigarrow_{\mathcal{X}} d \otimes f$  if and only if  $e \rightsquigarrow_{\mathcal{X}} f$*

Thus we can't use a PR box as a catalyst, even if we can freely use quantum correlations.

Questions...

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MK, 'Neither contextuality nor non-locality admits catalysts' (2021), [arXiv:2102.07637](https://arxiv.org/abs/2102.07637)