A generalized cohomology theory for quantum contextuality

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Linear constraint systems

A linear constraint system (LCS) is specified by a linear equation Mx = b over the ring \mathbb{Z}_d of integers mod d.

An operator solution consists of unitary matrices $A_i \in U_m$ that satisfy three conditions:

(1) d-torsion, (2) commutativity and (3) linear constraint.

Today's talk

Our goal is to introduce a generalized cohomology theory that can be used to classify operator solutions of LCSs.

- 1. Constructing a space of contexts
- 2. Interpreting operator solutions as maps
- 3. Stabilization and generalized cohomology
- 4. Mermin class

Satisfiability gap: For d odd are there LCSs which admit an operator solution over U_m for $m \ge 2$ but not over U_1 ?

Contexts in unitary groups

For us a context is a set

$$C = \{A_1, A_2, \cdots, A_n | A_i \in U_m\}$$

such that (1) *d*-torsion: $A_i^d = \mathbb{I}$ and (2) commuting: $A_i A_j = A_j A_j$.

We will think of contexts as group homomorphisms

$$C:\mathbb{Z}_d^n\to U_m.$$

Hypergraph formulation

A LCS Mx = b can be described by a pair (\mathfrak{H}, τ) consisting of

- 1. a set of vertices V encoding the variables x,
- 2. a set of edges E encoding the non-zero rows of M,
- 3. an incidence weight $\epsilon_e(v)$ encoding the matrix M,
- 4. a function $\tau: E \to \mathbb{Z}_d$ encoding the column *b*.

$$\begin{bmatrix} \vdots & & & \vdots \\ M_{k1} & \cdots & M_{ki} & \cdots & M_{kj} & \cdots & M_{kc} \\ \vdots & & & \vdots \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_c \end{bmatrix} = \begin{bmatrix} b_1 \\ \vdots \\ b_c \end{bmatrix}$$

Operator solutions and contextuality

An operator solution is a function $T: V \to U_m$ such that for each $e \in E$ the set $\{T(v) | v \in e\}$ is a context and

(3) linear constraint:
$$\prod_{v \in e} T(v)^{\epsilon_e(v)} = \omega^{\tau(e)} \mathbb{I} \qquad (\omega = e^{2\pi i/d})$$

A LCS is *contextual* if it admits an operator solution over U_m for $m \ge 2$ but does not admit an operator (*scalar*) solution over U_1 .

Ex. Mermin square and star LCSs are contextual for d = 2.



Topological realization

A topological realization for \mathfrak{H} is a connected 2-dimensional cell complex $X_{\mathfrak{H}}$ such that

- 1. 1-cells are labeled by V,
- 2. 2-cells are labeled by E,
- 3. attaching maps encode linear constraints (up to a scalar).





Homotopy and contextuality

The function $\tau: E \to \mathbb{Z}_d$ corresponds to $[\tau] \in H^2(X_{\mathfrak{H}}, \mathbb{Z}_d)$.

- 1. (\mathfrak{H}, τ) admits a scalar solution if and only if $[\tau] = 0$ for any topological realization $X_{\mathfrak{H}}$.
- 2. If (\mathfrak{H}, τ) admits an operator solution but no scalar solutions then any topological realization $X_{\mathfrak{H}}$ has a non-trivial fundamental group¹.

Generalizes Arkhipov's graph-theoretic characterization.

Can we interpret operator solutions in a topological way?

¹O. and Raussendorf. Quantum 4 (2020)

Space of contexts

Let B(d, m) denote the cell complex whose set of *n*-cells is given by *n*-tuples of contexts

 $\{C: \mathbb{Z}_d^n \to U_m | \text{ group homomorphism} \}$



Ex. $B(d, 1) = B\mu_d$ where $\mu_d = \{\omega^k | \ 0 \le k \le d - 1\}.$

²Adem and Gómez. Algebr. Geom. Topol. 15 (2015)

Classifying space for contextuality

Let $\overline{B}(d, m)$ denote the quotient space of B(d, m) obtained by

$$(A_1, \cdots, A_n) \sim (\alpha_1 A_1, \cdots, \alpha_n A_n) \quad \alpha_i \in \mu_d.$$

An operator solution $T: V \rightarrow U_m$ can be turned into a map

$$f_T: X_{\mathfrak{H}} \to \overline{B}(d,m).$$

Homotopy classes of maps induce an equivalence relation

$$T \sim T' \Leftrightarrow f_T \simeq f_{T'}.$$

Example - homotopic operator solutions



 f_T and $f_{T'}$ are homotopic as maps $S^1 \times S^1 \rightarrow \overline{B}(2,2^3)$.

Stabilization

It is hard to study homotopy classes of maps $X_{\mathfrak{H}} \to \overline{B}(d, m)$ but there is a (two step) procedure to resolve this difficulty: $\underbrace{\text{Step 1}}_{A \mapsto \binom{A = 0}{2}}$

$$U_1 \to U_2 \to \cdots \to U_m \xrightarrow{A \mapsto \begin{pmatrix} n & 0 \\ 0 & 1 \end{pmatrix}} U_{m+1} \to \cdots \to U_{\infty}$$

On the level of spaces we have

$$B(d,1)
ightarrow B(d,2)
ightarrow \cdots
ightarrow B(d,m)
ightarrow B(d,m+1)
ightarrow \cdots
ightarrow B(d,\infty)$$

To study $B(d, \infty)$ we need to pass to projectors.

Measurements associated to contexts

 $C = (A_1, A_2, \cdots, A_n)$ specifies a projective measurement

$$\Pi:\mathbb{Z}_d^n\to \operatorname{Proj}(\mathbb{C}^m)$$

where $\Pi(s_1 \cdots s_n)$ is the projector onto $V^{(1)}_{\omega^{s_1}} \cap V^{(2)}_{\omega^{s_2}} \cap \cdots \cap V^{(n)}_{\omega^{s_n}}$ where $V^{(i)}_{\omega^s}$ is the eigenspace of A_i corresponding to ω^s .

Stabilization gives a projective measurement

$$\Pi:\mathbb{Z}_d^n\to \mathsf{Proj}(\mathbb{C}^\infty)$$

where each $\Pi(s_1 \cdots s_n)$ projects onto a finite dimensional subspace.

Projections form a Γ-space

After stabilization, passing to projectors and imposing partial sum

$$\Pi_1 \perp \Pi_2 \ \Rightarrow \ \Pi_1 \oplus \Pi_2$$

we obtain a **Γ**-space

$$B(d,\infty) = \{C : \mathbb{Z}_d^n \to U_\infty\}_{\geq n}$$

$$\downarrow$$

$$k\mu_d = \{\Pi : \mathbb{Z}_d^n \to \mathsf{Proj}(\mathbb{C}^\infty)\}_{n \geq 0}$$

Every Γ -space³ gives a generalized cohomology theory.

³Segal. Topology 13 (1974)

Stabilization of $\overline{B}(d, m)$

The generalized cohomology theory we will use to label operator solutions of LCSs is obtained from $k\mu_d$.

Step 2

$$\begin{array}{c} B(d,m) & \dashrightarrow & k\mu_d \\ \downarrow & & \downarrow \\ \bar{B}(d,m) & \dashrightarrow & C(d,m) \end{array}$$

C(d, m) is a quotient of $k\mu_d$ in a suitable category of generalized cohomology theories.

C(d, m)-cohomology

(⁴) For a connected 2-dimensional cell complex

$$C(d,m)(X) \cong H^1(X,\mathbb{Z}_{(d,m)}) \oplus H^2(X,\mathbb{Z}_{(d,m)})$$

where (d, m) denotes the greatest common divisor.

For LCSs the second cohomology class coincides with $[\tau]$:

$$(\mathfrak{H}, \tau, T) \dashrightarrow f_T : X_{\mathfrak{H}} \to \overline{B}(d, m) \dashrightarrow (\varphi_1; \varphi_2) \in C(d, m)(X_{\mathfrak{H}})$$

⁴O. arXiv:2006.07542 (2020)

Mermin class

If d and m are coprime then every (\mathfrak{H}, τ) that admits an operator solution over U_m admits a scalar solution:

$$(d,m) = 1 \Rightarrow C(d,m)(X_{\mathfrak{H}}) = 0 \Rightarrow [\tau] = 0$$

Operator solution for the Mermin square LCS defines a class M_n

$$egin{aligned} \mathcal{C}(2,2^n)(\mathcal{S}^1 imes\mathcal{S}^1) &= \mathcal{H}^1(\mathcal{S}^1 imes\mathcal{S}^1,\mathbb{Z}_2)\oplus\mathcal{H}^2(\mathcal{S}^1 imes\mathcal{S}^1,\mathbb{Z}_2) \ &= (\mathbb{Z}_2)^2\oplus\mathbb{Z}_2. \end{aligned}$$

It turns out that the Mermin class $M_n = (0, 0; 1)$.

Interpretation of stable classes

For $m = d^n$ we have

$$C(d, d^n)(X) = H^1(X, \mathbb{Z}_d) \oplus H^2(X, \mathbb{Z}_d).$$

For d odd when does a stable class come from a LCS?

Real version $(\mathbb{C} \rightsquigarrow \mathbb{R})$ captures information about SPT phases

$$\mathbb{Z}_2 \xrightarrow[\langle Gu-Wen
angle} C_{\mathbb{R}}(2,2^n)(S^2) \longrightarrow \mathbb{Z}_2 \xrightarrow[\langle M_n
angle}$$

Thank you very much for your attention!