ALMOST EQUIVALENT PARADIGMS OF CONTEXTUALITY

LINDE WESTER

DEPARTMENT OF COMPUTER SCIENCE, UNIVERSITY OF OXFORD

linde.wester@cs.ox.ac.uk

1. INTRODUCTION

Contextuality of quantum mechanics entails the impossibility of assigning predetermined outcomes to observables, independently from the method of observation. We demonstrate how the sheaf-theoretic approach to contextuality by Abramsky and Brandenburger [1] translates to the equivalence-based approach by Spekkens [3]. This translation defines a categorical isomorphism. The two approaches describe non-contextuality for general operational theories, independently from the quantum formalism.

6. INDUCED GLOBAL SECTIONS

Tracing out different contexts gives statistically equivalent measurements. One can induce that non-contextuality implies **parameter independence**:

Here, $\xi_m|_{m'}(k')(\lambda) := \sum_{k:p_{m'}(k)=k'} \xi_m(k)(\lambda)$, for the projection $p_{m'}: O^m \to O^{m'}$.

An ontological representation is factorizable when for joint measurements $m = (m_1, ..., m_n)$ we can write $\xi_m(\lambda)(o) \prod_{i=1,...,n} \xi_{m_i}(\lambda)(\pi_i(o))$.

For every factorizable, non-contextual ontological representation B, there exists an empirical model A with states $\{\sigma_p\}$ and global sections d

One can show that $R^{NC}(A)$ and B realise the same operational theory.

2. THE SHEAF-THEORETIC APPROACH

Contextuality as a global inconsistency of joint measurements

Probability distributions over joint measurements form a presheaf

$$\mathcal{D}_{\mathbb{P}}\mathcal{E}:\mathcal{P}(X)^{op}\to Set$$

Here, X is a set of measurements, O^X the set of functions from *X* to an outcome set O, \mathcal{M} a cover of maximal joint measurements of *X*, and $\mathcal{D}_{\mathbb{P}}(X)$ is the set of probability distributions over X. We obtain the presheaf by composing the sheaf $\mathcal{E}: U \mapsto O^U$ with the functor

A state σ is given by a distribution $\sigma_C \in$ $\mathcal{D}_{\mathbb{P}}\mathcal{E}(C)$, for each measurement context $C \in \mathcal{M}$. It is **non-contextual** if it has a global section $d \in \mathcal{D}_{\mathbb{P}}\mathcal{E}(X)$. This is a joint distribution such that $\forall C \in \mathcal{M}$

$$\sum_{s' \in \mathcal{E}(X) | c = s} d(s') = \sigma_C(s)$$

contextual.

 $\mathcal{D}_{\mathbb{P}}(X) \xrightarrow{\mathcal{D}_{R}(f)} \mathcal{D}_{\mathbb{P}}(Y) :: d \mapsto [y \mapsto \sum d(x)]$

4. CANONICAL ONTOLOGICAL REPRESENTATIONS

Statistical equivalence does not affect contextuality in the sheaf approach.

A set of global sections $\{d^{\sigma}\}_{\sigma \in S}$ defines a non-contextual ontological representation $\tilde{R}^{NC}(A)$, based on statistical equivalence classes $[m] \in X / \sim$ where $\tilde{d}^{\tilde{\sigma}}([s]) := d^{\sigma}(s)$:

 $\Omega_A^{NC} := \mathcal{E}(X/\sim), \qquad \quad \mu_{\sigma}^{NC}(s) := \tilde{d}^{\sigma}([s]),$

We call this the 'canonical' ontological representation.

For two joint measurements m, n, $\xi_m|_{m \cap n} = \xi_n|_{m \cap n}$

 $\sigma_p(s) = \int_{\Omega} \xi_m(\lambda)(s(m))\mu_P(d\lambda), \qquad d(s) = \int_{\Omega} \prod_{m \in Min(M_B)} \xi_m(\lambda)\mu_P(d\lambda)$

An **empirical model** (X, \mathcal{M}, S) , where S is the set of states for X, \mathcal{M} , is non-contextual if all states are non-

$$\xi_m^{NC}(s)(k) := \delta_{[s]|_{[m]}([m]),[k]}$$

7. THEOREM

A categorical isomorphism

$$(\mathcal{E}(X), \{\sigma_m\}, \{\delta_{s(m),k} \\ \mathsf{Equivalence} \quad \mathcal{OR} \quad \mathsf{Forgetf} \\ \mathcal{E}mp \\ (X, \mathcal{M}, S) \quad \uparrow \quad (S, \downarrow \mathcal{N} \\ \mathsf{Isomorphism} \\ \mathsf{Isomorphism} \\ (S, \downarrow \mathcal{M}, \mathcal{M}) \\ \mathsf{Isomorphism} \\ \mathsf{Isomorph$$

For models with **sharp measurements** we have **functors** between the categories $\mathcal{E}mp$, of empirical models; OR, of ontological representations; and OT, of operational theories, which preserve non-contextuality.

8. CONCLUSIONS

- model.
- in [3].
- tuality in noise-free quantum circuits.



5. JOINT MEASUREMENTS

A set of N measurements $\{m_1, m_2, ..., m_N\}$ is **jointly measurable** if there exists a measurement *m* with the following features [2]:

- $\{m_1, ..., m_N\}$
- bution of *m*.

Here, π_S is the projection function on the subspace $\mathcal{M}(m_S) \subset \mathcal{E}(m)$

3. THE EQUIVALENCE-BASED APPROACH

Contextuality as an ontological distinction between operationally equivalent operations

Operational theories (P, M, d) are sets P, M, of preparations and measurements, with probability distributions

 $d(p,m): O \to [0,1] \qquad \forall (p,m) \in P \times M$

Ontological representations (Ω, μ, ξ) , consist of a set of ontological values Ω , together with a set of probability distributions

$$\mu = \{\mu_p : \Omega \to [0,1]\}_{p \in P}$$

$$\xi = \{\xi_m(\lambda) : O^m \to [0,1]\}_{\lambda \in \Omega, m \in M}$$

s.t.
$$\int_{\Omega} \xi_m(\lambda) \mu_p(d\lambda) = d_A(p,m)$$
$$\forall p \in P, m \in M$$

• Sheaf-theoretic non-contextuality corresponds to the existence of a factorizable non-contextual ontological representation in the equivalence-based

• The two formalisms agree on classic examples of contextuality, as well as contextuality for preparations and for unsharp measurements introduced

• The canonical ontological representation provides a framework for contex-



• The outcome set of *m* is the Cartesian product of the outcome sets of

• The outcome distributions are recovered as marginals of the outcome distri-

 $\forall S, \forall p : p(k_S | m_S; p) = \sum_{k \in O^m: \pi_S(k) = k_S} p(k | m; p)$

An ontological representation is **noncontextual** if it is defined on statistical equivalence classes of preparations and measurements: $\forall n \in \overline{M}, q \in P$

| $p \sim p'$ | \Leftrightarrow | $d(p,n) = d(p^\prime,n)$ |
|----------------------|-------------------|--------------------------|
| $m\sim m'$ | \Leftrightarrow | d(q,m) = d(q,m') |
| $(m,k) \sim (m',k')$ | \Leftrightarrow | d(q,m)(k) = d(q,m')(k') |

Preparation non-contextuality: $p \sim p' \Rightarrow \mu_p = \mu_{p'}$ **Measurement non-contextuality:** $(m,k) \sim (m',k') \Rightarrow \xi_{k,m} = \xi_{k',m'}.$

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